Int main

Speed =

Bkspeed=

Rest=

Mav instead of motor speed as a battery %

Enable servos

Turn motors on

Camera on (if we are using a camera)

Distance travelled from x to y (when chosen to will save to variable)

Func open servos (claws)

Func close servos (claws)

Func camera colordetecc

func 180 turn left

func 180 turn right

func 360 rightwards