Int main

Speed =

Bkspeed=

Rest=

Mav instead of motor speed as a battery %

Enable servos

Turn motors on

Camera on (if we are using a camera)

Turn 45 degrees right

Go towards yellow block

When distance 2900

Bring yellow block away

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Go to palm

Knock down thee pompoms of palms

Drive forward while its spinning (fidget spinner thing)

Do it on the other side

--

Water for water repository

Go to water deposit place

Open partially,

Next deposit,

Open fully

--

Take pom poms dropped from palm trees, (collect(eat))

Bring them to redzone

Go to black linepom poms

Take to red zone

--

Distance travelled from x to y (when chosen to will save to variable)

Func open servos (claws)

Func close servos (claws)

Func camera colordetecc

func 180 turn left

func 180 turn right

func 360 rightwards

Servo positions open:

Servo 0, 299

Servo 1,729